Block Abstraction Memoization with Copy-On-Write Refinement

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05.09.2017







Basic Problem with Software Verification

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computation of abstract state space at once is expensive

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- use a *cache* for intermediate results

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Benefits of BAM:

- implemented as top-level CPA
- independent of sub-analysis (PA, VA, IA,... and combinations)
- modular approach: optimization and heuristics

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Basics of BAM: Structure and Components

CFA divided into blocks

- functions or loops as block size
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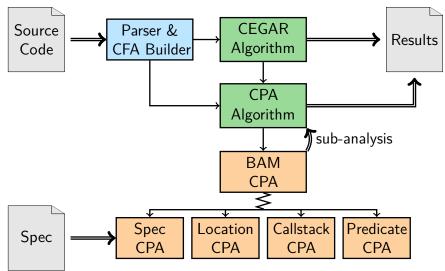
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Combine with other components:

- CEGAR: specialized refinement (over several ARGs)
- Exporter: ARG & Graphml

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Overview of the CPACHECKER Framework



- \blacktriangleright spurious error path found \rightarrow refinement procedure
 - \rightarrow determines a new precision and a cutpoint
 - \rightarrow only a "minimal" part of the ARG is remove

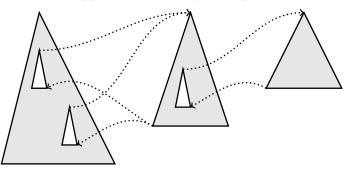
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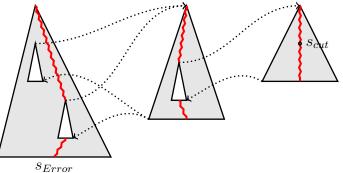
BAM Refinement

- determine precision and cutpoint over several nested ARGs
- depends only on underlying analysis
- refine the "minimal" set of ARGs
- several heuristics:
 - ▶ refine one, all, or some ARGs along error-path
 - merge precisions from different sources

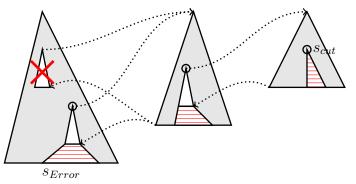
Default state space exploration in BAM with refinement, refinement applied with an *in-place* update of the ARG



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Default state space exploration in BAM with refinement, refinement applied with an *in-place* update of the ARG



What is a *repeated counterexample*?

- an error path cannot be excluded from repeated exploration
- cycles of error paths (and refinements)
 - \rightarrow no progress in CEGAR

Observation

- problem mostly appears with "big" programs,
 e.g. with many blocks and several refinements
- small changes in programs cause large differences in runtime of BAM

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Manual analysis shows *possible reasons*

- deleting block abstractions (*holes* in the ARG)
- imprecise caching (aggressive caching) \rightarrow heuristics
- imprecise reducer (Predicate Analysis) \rightarrow heuristics

The old Approach

- And after the refinement?
 - start exploration again
 - when accessing a missing block, recompute it or use another block abstraction from cache

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Problem?

- interfering with other refinements
 - \rightarrow precision for a missing block?
 - \rightarrow re-compute nested blocks or take from cache?
- exporting incomplete data (witnesses, ARGs, statistics)

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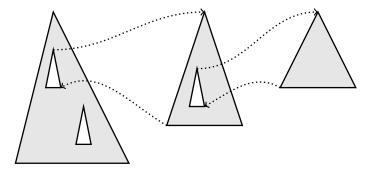
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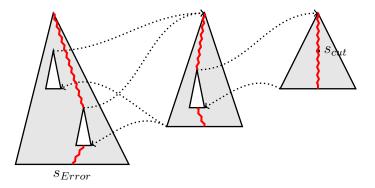
Idea: do not delete computed block abstractions

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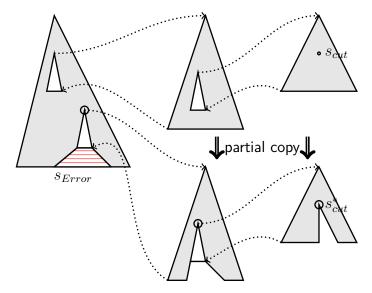
Use Copy-on-Write for Updates of the ARG



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Computational overhead?

- \blacktriangleright old approach: removing a subtree needs O(N) time
- new approach: copying a subtree needs O(N) time
- only small increase in memory consumption:

 \rightarrow *flat copy* of ARG states

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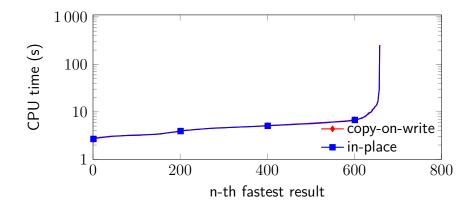
More benefits

- no need to re-computate deletes blocks
- all information available at end of analysis
- immutable ARGs (after finished sub-analysis)

Evaluation (<=1 refinements)

Runtime of refinement approaches of BAM with predicate analysis

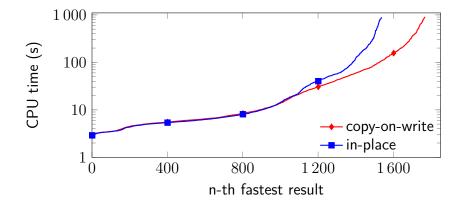
tasks with up to one refinement \rightarrow no difference expected!



Evaluation (>1 refinements)

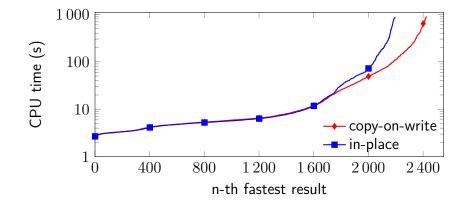
Runtime of refinement approaches of BAM with predicate analysis

tasks with more than one refinement



Evaluation (<=1 and >1 refinements combined)

Runtime of refinement approaches of BAM with predicate analysis



Conclusion

Current status:

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Future work:

- some heuristics might no longer be beneficial
- new: choose from several cache-entries for the same key?
- merge into trunk, maybe soon :-)